Abstraction: The Process

In this note, we discuss one of the most fundamental abstractions that the OS provides to users: the **process**. The definition of a process, informally, is quite simple: it is a **running program** [V+65,B70]. The program itself is a lifeless thing: it just sits there on the disk, a bunch of instructions (and maybe some static data), waiting to spring into action. It is the operating system that takes these bytes and gets them running, transforming the program into something useful.

It turns out that one often wants to run more than one program at once; for example, consider your desktop or laptop where you might like to run a web browser, mail program, a game, a music player, and so forth. In fact, a typical system may be seemingly running tens or even hundreds of processes at the same time. Doing so makes the system easy to use, as one never need be concerned with whether a CPU is available; one simply runs programs. Hence our challenge:

THE CRUX OF THE PROBLEM: HOW TO PROVIDE THE ILLUSION OF MANY CPUS? Although there are only a few physical CPUs available, how can the OS provide the illusion of a nearly-endless supply of said CPUs?

The OS creates this illusion by **virtualizing** the CPU. By running one process, then stopping it and running another, and so forth, the OS can promote the illusion that many virtual CPUs exist when in fact there is only one physical CPU (or a few). This basic technique, known as **time sharing** of the CPU, allows users to run as many TECHNIQUE: TIME SHARING (AND SPACE SHARING) **Time sharing** is one of the most basic techniques used by an OS to share a resource. By allowing the resource to be used for a little while by one entity, and then a little while by another, and so forth, the resource in question (e.g., the CPU, or a network link) can be shared by many. The natural counterpart of time sharing is **space sharing**, where a resource is divided (in space) among those who wish to use it. For example, disk space is naturally a space-shared resource, as once a block is assigned to a file, it is not likely to be assigned to another file until the user deletes it.

concurrent processes as they would like; the potential cost is performance, as each will run more slowly if the CPU(s) must be shared.

To implement virtualization of the CPU, and to implement it well, the OS will need both some low-level machinery as well as some high-level intelligence. We call the low-level machinery **mechanisms**; mechanisms are low-level methods or protocols that implement a needed piece of functionality. For example, we'll learn below how to implement a **context switch**, which gives the OS the ability to stop running one program and start running another on a given CPU; this **time-sharing** mechanism is employed by all modern OSes.

On top of these mechanisms resides some of the intelligence in the OS, in the form of **policies**. Policies are algorithms for making some kind of decision within the OS. For example, given a number of possible programs to run on a CPU, which program should the OS run? A **scheduling policy** in the OS will make this decision, likely using historical information (e.g., which program has run more over the last minute?), workload knowledge (e.g., what types of programs are run), and performance metrics (e.g., is the system optimizing for interactive performance, or throughput?) to make its decision.

4.1 The Abstraction: A Process

The abstraction provided by the OS of a running program is something we will call a **process**. As we said above, a process is simply a running program; at any instant in time, we can summarize a process by taking an inventory of the different pieces of the system it accesses or affects during the course of its execution.

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DESIGN TIP: SEPARATION OF POLICY/MECHANISM In many operating systems, a common design paradigm is to separate high-level policies from their low-level mechanisms [L+75]. You can think of the mechanism as providing the answer to a *how* question about a system; for example, *how* does an operating system perform a context switch? The policy provides the answer to a *which* question; for example, *which* process should the operating system run right now? Separating the two allows one easily to change policies without having to rethink the mechanism and is thus a form of **modularity**, a general software design principle.

To understand what constitutes a process, we thus have to understand its **machine state**: what a program can read or update when it is running. At any given time, what parts of the machine are important to the execution of this program?

One obvious component of machine state that comprises a process is its *memory*. All instructions lie in memory; the data that the running program reads and updates sits in memory as well. Thus the memory that the process can address (sometimes called its **address space**) is part of the process.

Also part of the process's machine state are *registers*; many instructions explicitly read or update registers and thus clearly they are important to the execution of the process.

Note that there are some particularly special registers that form part of this machine state. For example, the **program counter** (**PC**) (sometimes called the **instruction pointer** or **IP**) tells us which instruction of the program is currently being executed; similarly a **stack pointer** and associated **frame pointer** are used to manage the stack for function parameters, local variables, and return addresses.

Finally, programs often access persistent storage devices too. Such *I/O information* might include a list of the files the process currently has open.

4.2 Process API

Though we defer discussion of a real process API until a subsequent chapter, here we first give some idea of what must be included in any interface of an operating system.

- **Create:** An operating system must include some method to create new processes. When you type something at a shell, or double-click on an application icon, the OS is invoked to create a new process to run the program you have indicated.
- **Destroy:** As there is an interface for process creation, systems also provide an interface to destroy processes forcefully. Of course, many processes will run and just exit by themselves when complete; when they don't, however, the user may wish to kill them, and thus an interface to halt a runaway process is quite useful.
- Wait: Sometimes it is useful to wait for a process to stop running; thus some kind of waiting interface is often provided.
- **Miscellaneous Control:** Other than killing or waiting for a process, there are sometimes other controls that are possible. For example, most operating systems provide some kind of method to suspend a process (stop it from running for a while) and then resume it (continue it running).
- **Status:** There are usually interfaces to get some status information about a process as well, such as how long it has run for, or what state it is in.

4.3 Process States

Now that we have some idea of what a process is (though we will continue to refine this notion), let us talk about the different **states** a process can be in at a given time. The notion that a process can be in one of these states arose in early computer systems [V+65,DV66].

In a simplified view, a process can be in one of three states:

- **Running**: In the running state, a process is running on a processor. This means it is executing instructions.
- **Ready**: In the ready state, a process is ready to run but for some reason the OS has chosen not to run it at this given moment.
- **Blocked**: In the blocked state, a process has performed some kind of operation that makes it not ready to run until some other event takes place. A common example: when a process initiates an I/O request to a disk, it becomes blocked and thus some other process can use the processor.

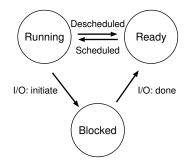


Figure 4.1: Process: State Transitions

If we were to map these states to a graph, we would arrive at the diagram in Figure 4.1. As you can see in the diagram, a process can be moved between the ready and running states at the discretion of the OS. Being moved from ready to running means the process has been **scheduled**; being moved from running to ready means the process has been **descheduled**. Once a process has become blocked (e.g., by initiating an I/O operation), the OS will keep it as such until some event occurs (e.g., I/O completion); at that point, the process moves to the ready state again (and potentially immediately to running again, if the OS so decides).

4.4 Data Structures

The OS is a program, and like any program, it has some key data structures that track various relevant pieces of information. To track the state of each process, for example, the OS likely will keep some kind of **process list** for all processes that are ready, as well as some additional information to track which process is currently running. The OS must also track, in some way, blocked processes; when an I/O event completes, the OS should make sure to wake the correct process and make it ready to run again.

DATA STRUCTURE: THE PROCESS LIST

Operating systems are replete with various important **data structures** that we will discuss in these notes. The **process list** is the first such structure. It is one of the simpler ones, but certainly any OS that has the ability to run multiple programs at once will have something akin to this structure in order to keep track of all the running programs in the system. Sometimes people refer to the individual structure that stores information about a process as a **Process Control Block (PCB**).

Figure 4.2 shows what type of information an OS needs to track about each process in the xv6 kernel [CK+08]. Similar process structures exist in "real" operating systems such as Linux, Mac OS X, or Windows; look them up and see how much more complex they are.

From the figure, you can see a couple of important pieces of information the OS tracks about a process. The **register context** will hold, for a stopped process, the contents of its register state. When a process is stopped, its register state will be saved to this memory location; by restoring these registers (i.e., placing their values back into the actual physical registers), the OS can resume running the process. We'll learn more about this technique known as a **context switch** in future chapters.

You can also see from the figure that there are some other states a process can be in, beyond running, ready, and blocked. Sometimes a system will have an **initial** state that the process is in when it is being created. Also, a process could be placed in a **final** state where it has exited but has not yet been cleaned up (in UNIX-based systems, this is called the **zombie** state¹). This final state can be useful as it allows other processes (usually the **parent** that created the process) to examine the return code of the process and see if it executed successfully. When finished, the parent will then make one final call to indicate to the OS that it can completely forget about the now-extinct process (the UNIX wait () system call does this).

¹Yes, the zombie state. Just like real zombies, these zombies are relatively easy to kill. However, different techniques are usually recommended.

ABSTRACTION: THE PROCESS

```
// the registers xv6 will save and restore
// to stop and subsequently restart a process
struct context {
 int eip;
 int esp;
  int ebx;
 int ecx;
 int edx;
 int esi;
 int edi;
 int ebp;
};
// the different states a process can be in
enum proc_state { UNUSED, EMBRYO, SLEEPING,
                  RUNNABLE, RUNNING, ZOMBIE };
// the information xv6 tracks about each process
// including its register context and state
struct proc {
 char *mem;
                              // Start of process memory
 uint sz;
                              // Size of process memory
 char *kstack;
                              // Bottom of kernel stack
                              // for this process
                              // Process state
 enum proc_state state;
                              // Process ID
  int pid;
                              // Parent process
 struct proc *parent;
 void *chan;
                              // If non-zero, sleeping on chan
 int killed;
                              // If non-zero, have been killed
 struct file *ofile[NOFILE]; // Open files
                       // Current directory
xt; // Switch here to run process
 struct inode *cwd;
  struct context context;
                              // Trap frame for the
 struct trapframe *tf;
                              // current interrupt
};
```

Figure 4.2: The xv6 Proc Structure

4.5 Summary

We have introduced the most basic abstraction of the OS: the process. It is quite simply viewed as a running program. With this conceptual view in mind, we will now move on to the nitty-gritty: the low-level mechanisms needed to implement processes, and the higher-level policies required to schedule them in an intelligent way. By combining mechanisms and policies, we will build up our understanding of how an operating system virtualizes the CPU.

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References

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[DV66] "Programming Semantics for Multiprogrammed Computations" Jack B. Dennis and Earl C. Van Horn Communications of the ACM, Volume 9, Number 3, March 1966 This paper defined many of the early terms and concepts around building multiprogrammed systems.

[H70] "The Nucleus of a Multiprogramming System" Per Brinch Hansen Communications of the ACM, Volume 13, Number 4, April 1970 This paper introduces one of the first **microkernels** in operating systems history, called Nucleus. The idea of smaller, more minimal systems is a theme that rears its head repeatedly in OS history; it all began with Brinch Hansen's work described herein.

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